

Amendments to the Claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1. (Currently amended) An inspection system for coiled tubing being employed in a well, the system comprising:
 - an imaging device recording a video signals-signal of a segment of the coiled tubing as the coiled tubing is being injected into or removed from the well;
 - a conductor transmitting the video signals-signal to an image grabber;
 - the image grabber generating images of the tubing segment from the video signals-signal; and
 - a program in the processor configured to execute pattern recognition software and analyze each image separately to detect discrete anomalies of the tubing segment.
2. (Original) The system of claim 1 further including means for generating longitudinal coordinates of the tubing segment.
3. (Original) The system of claim 2 wherein the longitudinal coordinates of the tubing are stamped on the image of the tubing segment.
4. (Original) The system of claim 1 wherein the video signals have a minimum resolution of 640 X 480 pixels with an 8 bit per pixel color or grayscale depth.
5. (Original) The system of claim 1 further including a video stacker stacking the images.
6. (Previously presented) The system of claim 1 wherein the processor is programmed to recognize and classify the discrete anomalies on the tubing segment shown in the images.
7. (Previously presented) The system of claim 1 wherein the discrete anomalies include one or more of the following: wear, cracks, patterns, abrasions, color, discolorations, or dimensions.

8. (Previously presented) The system of claim 1 wherein the program in the processor analyzes the images to detect the diameter of the tubing.

9. (Previously presented) The system of claim 1 wherein the processor generates a signal upon detecting a discrete anomaly in the tubing so as to provide a warning of such discrete anomaly.

10. (Canceled)

11. (Canceled)

12. (Canceled)

13. (Currently amended) An inspection system comprising:

a composite coiled tubing having layers of fibers forming a tubing wall, the outermost layer having a longitudinal stripe;

an imaging device recording a video signals-signal of a segment of the coiled tubing as the coiled tubing is presented before the imaging device;

a processor receiving the video signals-signal from the imaging device; and

a program in the processor analyzing each image of the video signals-signal separately to detect a circumferential position of a defect in reference to the stripe on the tubing segment.

14. (Currently Amended) The system of claim 13 wherein the tubing has at least one outer layer having a predetermined color and the program analyzes the video signals-signal to detect the predetermined color on the tubing segment.

15. (Currently amended) An automated inspection system for identifying defects in coiled tubing, comprising:

a plurality of imaging devices each configured to ~~capture video images~~ record a video signal of coiled tubing as the tubing passes in front of the imaging devices; and

a computer system configured to execute pattern recognition software to analyze ~~each image~~ the images from the video signals separately, extract discrete anomalies from each image, and generate an indication if a discrete anomaly is identified as a defect in an image.

16. (Original) The inspection system of claim 15 wherein the imaging devices are ~~fiber-optic~~ imaging devices.

17. (Original) The inspection system of claim 15 wherein the plurality of imaging devices consist of three CCD cameras.

18. (Original) The inspection system of claim 15 further comprising:

a counter signal identifying a location along the coiled tubing; and

the computer system reading the counter signal to identify the location along the coiled tubing at which a defect is located.

19. (Original) The inspection system of claim 18 wherein if the counter signal indicates that the coiled tubing is not moving or moving slower than a threshold, the inspection system is disabled.

20. (Previously presented) The inspection system of claim 18 wherein if the counter signal indicates that the coiled tubing is moving faster than a threshold, the inspection system is enabled.

21. (Currently Amended) The inspection system of claim 18 further comprising a video stacker configured to correlate ~~video~~ the images taken from the plurality of imaging devices with one another as well as with a longitudinal position along the coiled tubing using the counter signal.

22. (Currently Amended) The inspection system of claim 15 wherein the ~~video~~-images are transmitted to the computer system for real time identification of defects.

23. (Currently Amended) The inspection system of claim 15 further comprising a video recorder configured to store the ~~video~~-images from the plurality of imaging devices for later defect identification.

24. (Previously presented) The inspection system of claim 15 wherein the coiled tubing comprises at least one longitudinal stripe on the outer surface of the tubing as a reference for the purpose of identifying the annular location of a discrete anomaly on the tubing.

25. (Original) The inspection system of claim 15 wherein the pattern recognition software further measures the outside diameter of the tubing and generates an indication if the diameter is outside a user-designated tolerance range.

26. (Currently amended) A computer system for use in an automated tubing inspection system comprising:

a processor;

at least one output device producing ~~video signals~~ a video signal of the tubing surface;

an input device configured to receive the video ~~signals~~ signal and generate sequential images of the tubing surface from the video ~~input signal~~;

a pattern classification software program configured to read each image separately and extract a discrete anomalies-anomaly of the tubing from ~~the images~~ an image and compare the size of ~~these the~~ discrete anomalies-anomaly against a user-defined thresholds threshold;

wherein if the pattern classification software determines that the size of the discrete ~~anomalies-anomaly~~ does not fall within the user-defined threshold, the software generates an interrupt indicating that a defect has been located.

27. (Previously presented) The computer system of claim 26 further comprising:
 markings on the coiled tubing providing location data on the coiled tubing;
 an input for receiving the location data indicating the position from which the incoming images are taken;
 wherein when the pattern classification software generates the warning interrupt, the computer system transmits the image containing the defect and the corresponding location data to the output device.
28. (Previously presented) The computer system of claim 27 wherein the output device is a printer.
29. (Previously presented) The computer system of claim 27 wherein the output device is a monitor.
30. (Previously presented) The computer system of claim 27 wherein the pattern classification software may be trained to recognized unwanted defects and ignore innocuous discrete anomalies.
31. (Previously presented) A method of identifying discrete anomalies in a continuous length of coiled tubing, comprising:
 passing the continuous length of coiled tubing in front of a plurality of imaging devices;
 capturing images of the outer circumference of the tubing with the imaging devices and transmitting the images to a processor;
 receiving the images by the processor and inputting the images to computer vision software running on the processor; and
 processing each image separately on the computer vision software; and
 identifying predetermined discrete anomalies in the tubing in each image.
32. (Previously presented) The method of claim 31 further including initiating a warning event upon detecting a discrete anomaly in the tubing.

33. (Previously presented) The method of claim 31 wherein the passing step includes guiding the coiled tubing through a guide roller mechanism as the tubing is spooled on or off a storage reel and placing the aperture of a plurality of imaging devices in close proximity to the guide roller mechanism.

34. (Previously presented) The method of claim 31, further comprising:
transmitting a depth counter value to the processor to identify the position along the tubing at which the images are taken; and
displaying the image of the discrete anomalies.

35. (Previously presented) The method of claim 34 further including markings indicating the position of the discrete anomalies in the tubing.

36. (Previously presented) A method of identifying discrete anomalies in a continuous length of coiled tubing, comprising:
passing the continuous length of coiled tubing in front of a plurality of imaging devices;
capturing images of the outer circumference of the tubing with the imaging devices and transmitting the images to a processor;
receiving the images by the processor and inputting the images to computer vision software running on the processor;
processing each image separately on the computer vision software;
identifying predetermined discrete anomalies in the tubing in each image;
specifying the annular location of a discrete anomaly with respect to an annular reference established by at least one longitudinal stripe located on the outer diameter of the tubing; and
indicating the annular position of the discrete anomaly.

37. (Previously presented) The method of claim 31, further comprising transmitting power to operate the imaging devices and transmitting light to illuminate the tubing.

38. (Previously presented) The method of claim 31, wherein the imaging devices are located on a levelwind that is coupled to a reel on which the tubing is coiled.

39. (Previously presented) The method of claim 31, further comprising storing the images on recordable media prior to processing the images.

40. (Previously presented) The method of claim 39, further comprising storing the images with the depth counter value.

41. (Previously presented) The method of claim 31, further comprising identifying a discrete anomaly as a defect by determining if the size of the discrete anomaly exceeds a user-designated threshold.

42. (Previously presented) The method of claim 31, further comprising identifying a discrete anomaly as a defect by determining if the size of a previously recognized discrete anomaly has grown beyond a user-designated percentage of its original size.

43. (Previously presented) The system of claim 1 wherein the coiled tubing comprises an outer wear layer and a contrasting layer beneath the outer wear layer where if the outer wear layer is worn away, the contrasting layer becomes visible as a contrasting feature on the tubing.

44. (Previously presented) The system of claim 43 wherein the coiled tubing further comprises a stripe located on the outer wear layer and parallel to the longitudinal axis of the tubing.

45. (Previously presented) The system of claim 44 wherein the coiled tubing comprises more than one stripe located on the outer wear layer and wherein the stripes are individually distinguishable.